

Geomorphometry: Today and Tomorrow

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relationships among topographic features and this state-of-affairs helps to explain why all computed surface networks are scale-dependent, fuzzy, and vague and why their undisputed calculation remains elusive [2].

The transition from cartographic to remote sensing data sources and the associated consequences – the large coverage and fine resolutions afforded by many of these new DEMs – has brought numerous changes to the typical digital terrain modeling workflow. The potential benefits are enormous: the ASTER and SRTM DEMs, for example, provide coverage for much of the globe at the 30 m resolution that could only be used for small and moderate-sized catchments until relatively recently and LiDAR provides large numbers of high-density mass points which, if processed appropriately, can provide 1-3 m DEMs with high vertical accuracy and the preservation of the terrain structure (i.e. the shape).

This transition means that most of us will not collect our own source data and prepare our own DEMs going forward and this will place an increased emphasis on the provenance of both the original data and the methods applied to them and the expertise of the people contributing the DEMs. This focus on provenance will improve the reproducibility and encourage users to consider questions surrounding the credibility (i.e. fitness-of-use) of the content for the task(s) at hand [3].

The calculation and use of land surface parameters constitute the heart of geomorphometry as we know it today. There is now more than 100 primary and secondary land surface parameters in common use [4]. The majority are primary parameters derived from square-grid DEMs which measure site-specific, local or regional characteristics without additional input. The secondary parameters are derived from ≥ 2 of the primary parameters and additional inputs in some instances, and focus on water flow/soil redistribution or energy/heat regimes. Many of these land surface parameters incorporate flow direction and therefore make use of one or more of the 44 flow direction algorithms have been proposed during the past 33 years. Several of the newer algorithms combine square-grids and TINs to avoid the shortcomings associated with square-grid DEMs and to take advantage of the additional discretization provided by TINs. However, it is difficult to assess the efficacy of these flow direction algorithms, and their impact on flow accumulation and the other land surface parameters which incorporate them. Buchanan et al. [5], for example, recently calculated topographic wetness using >400 unique approaches that considered different DEM resolutions, the vertical precision of the DEM, flow

Abstract—This paper summarizes the current state-of-the-art in geomorphometry and describes the innovations that are close at hand and will be required to push digital terrain modeling forward in the future. These innovations will draw on concepts and methods from computer science and the spatial sciences and require greater collaboration to produce “actionable” knowledge and outcomes.

I. INTRODUCTION

Great strides have been in digital terrain modeling during the past 50 years spurred on by new sources of digital elevation data, the increasing use of theory to guide digital terrain modeling workflows, the specification of many new land surface parameters, the identification and extraction of landforms and other land surface objects, the improving characterization of error and uncertainty, and the development and sharing of new computer code to facilitate and support digital terrain modeling workflows. The rate of development has surged during the past 15 years, motivated by pressing environmental challenges at the meso- and topo-scales and the rapidly evolving computational resources that are now available to support digital terrain modeling applications.

The remainder of this paper is divided into three parts. The first summarizes the current state-of-the-art, the second describes the innovations that are close at hand and will be required to push digital terrain modeling forward in the future, and the third offers some conclusions.

II. CURRENT STATE-OF-THE-ART

Most digital terrain modeling applications in biogeography, climatology, ecology, geology, geomorphology, hydrology, pedology and natural hazards are scale-specific and the results will vary with the scale over which they are cast. The user is then left with the dilemma that they cannot determine whether the failure of a model to fit perfectly is due to the model itself, or to the relatively ‘coarse’ resolution of the elevation data, or both [1]. Relatively little attention has been given to the topological

88 direction and slope algorithms, smoothing versus low-pass
89 filtering and the inclusion of relevant soil properties, and
90 compared the resulting topographic wetness maps with observed
91 soil moisture in agricultural fields.

92 Some applications have also focused on the extraction and
93 classification of landforms and land surface objects. Fuzzy
94 classification methods have featured prominently in these
95 applications because many of the land surface objects and
96 landforms that are of interest have fuzzy boundaries. Several
97 others have attempted to automate and extend Hammond's [6]
98 map of repeating landform patterns for the conterminous U.S. to
99 the globe [7]. And finally, Dragut and Eisank [8] borrowed
100 concepts from remote sensing and data science to first segment
101 the DEM and then classify the objects to avoid the problems of
102 working directly with the DEM grid cells when extracting and
103 classifying landforms and other land surface objects.

104 A number of recent applications have also tackled sources of
105 error, the various ways uncertainty can be estimated and handled
106 in terrain modeling workflows, how this knowledge can be used
107 to assess 'fitness-for-use' in specific applications, and the new
108 opportunities for multi-scale analysis and cross-scale inference
109 afforded by the increasing availability of DEMs across a broad
110 range of scales. A series of stellar case studies shows how the
111 measurement of error and uncertainty accompanying terrain
112 modeling workflows might be used to improve our understanding
113 of predictive vegetation modeling [9], soil redistribution resulting
114 from water erosion [10], how catchment area calculations, slope
115 estimates and numerical simulations of landscape development
116 [11] and the soil-water-vegetation interactions in the LPJ-GUESS
117 dynamic ecosystem model [12] are influenced by the choice of
118 flow direction algorithm, and how a new sub-grid TOPMODEL
119 parameterization and the associated uncertainties influence the
120 modeling of the spatiotemporal dynamics of global wetlands
121 [13]. More applications like these will be needed in the future.

122 All of the aforementioned applications are enabled by
123 software that supports the calculation of land surface parameters
124 and the extraction and classification of landforms and other land
125 surface objects. Six systems – ArcGIS, GRASS, QGIS, SAGA,
126 TauDEM, and the Whitebox Geospatial Analysis Tools – stand
127 out today because of the large numbers of terrain tools included,
128 the availability of GIS functions, the large numbers of data
129 formats supported, and the high level of interoperability.

130 III. FUTURE NEEDS AND OPPORTUNITIES

131 A. Provenance, Credibility, and Application-Context 132 Knowledge

133 The rapid emergence of the web and all this entails (i.e. web
134 portals for sharing geospatial datasets, the provision of software

135 as a service, etc.) coupled with advances in our knowledge and
136 understanding of error and uncertainty and how these concepts
137 can be used to clarify the 'fitness-for-use' of digital terrain
138 modeling tools and data for specific applications bring both
139 provenance and credibility to the fore. These elements have
140 traditionally been handled by metadata in the spatial sciences and
141 it will be important for the geomorphometry community to adopt
142 and use metadata to describe digital terrain modeling methods
143 and datasets going forward. However, this metadata may be
144 necessary but not sufficient, and Qin et al. [14] recently used
145 case-based formalization and reasoning methods to acquire
146 'application-context' knowledge. They selected 124 cases of
147 drainage network extraction (50 for evaluation and 74 for
148 reasoning) from peer reviewed journal articles and using these
149 cases to determine the catchment area threshold for extracting
150 drainage networks.

151 B. Rediscovering and Using What We Already Know

152 The development of global elevation datasets has brought into
153 focus what geographers have long known; namely, the need to
154 choose your map projections and coordinate systems carefully to
155 suit the geographic extent of the study area of interest. The
156 general strategy should be one in which spherical equal angular
157 DEMs are chosen for large study areas (i.e. the globe, continents,
158 and the catchments of large rivers) and planar square-grid DEMs
159 are chosen for small and moderate-sized catchments. Most of
160 today's methods were developed for planar square-grid DEMs,
161 but Guth [15] and others have proposed algorithms for
162 calculating some land surface parameters for spherical equal
163 angular DEMs.

164 C. Developing New Digital Terrain Modeling Methods

165 The continued development of new digital terrain modeling
166 methods like the three examples highlighted below is likely to
167 yield substantial benefits. Krebs et al. [16] recently proposed a
168 new method to assess the vertical transverse and profile curvature
169 that provides new opportunities to measure and visualize these
170 two land surface parameters over a large range of scales. Byun
171 and Seong [17] proposed a new maximum depth tracing
172 algorithm to extract more accurate stream longitudinal profiles
173 using depression-unfilled DEMs, and Buttenfield et al. [18]
174 compared planar distance with 8 measures of surface adjusted
175 distance to check whether or not the common assumption, that
176 the improvements in distance estimation are so small that surface
177 adjustment is not warranted, is true (or not) for specific
178 applications.

179 D. Clarifying and Strengthening the Role of Theory

180 The emergence of fine resolution elevation data, such as
181 LiDAR, also provides new opportunities to assess fundamental

182 questions about landscape form and evolution in geomorphology
183 as well as other domains. There are two primary ways to proceed
184 here. The first uses theory to guide the workflow that is chosen,
185 whereas the second relies on experiments to test one or more of
186 our existing theories.

187 The first approach seeks to take advantage of our existing
188 knowledge of how processes work. Clubb et al. [19], for
189 example, have proposed a new algorithm for predicting channel
190 head locations that is partly informed by the stream power
191 equation, which is a detachment-limited model that proposes that
192 the fluvial incision rate is proportional to stream power, which
193 represents the energy expenditure of the flow.

194 The second approach noted above seeks to test existing
195 theory and can be illustrated using the work of Jensco and
196 McGlynn [20] which tested the relationship between upslope
197 contributing area and the existence and longevity of the hillslope-
198 riparian-stream shallow groundwater connectivity for a series of
199 transects and the stream network for several watersheds in
200 Montana. The results showed how the internal catchment
201 landscape structure acts as a first-order control on runoff source
202 area and catchment response in these types of landscapes.

203 *E. Developing High-fidelity Multi-resolution DEMs*

204 The importance of multi-scale analysis and cross-scale
205 inference will grow in the future. These applications rely on the
206 availability of high-fidelity, multi-resolution DEMs and methods
207 to build such DEMs. Some progress has been made but most of
208 this work is motivated by the need or desire for accurate
209 topographic representation across a relatively narrow range of
210 geographic scales. There are two challenges. The first concerns
211 the types of surfaces represented with some of the new radar and
212 stereo optical imagery sources. The default surface is the top of
213 the structures or vegetation and many, but not all, geomorphic
214 applications will need a bare earth DEM. The second is the need
215 for high-fidelity, multi-resolution DEMs that work with global
216 environmental simulations which adopt sub-grid schemes to
217 express topographic heterogeneity [21]. These sub-grid schemes
218 are typically designed for empirical parameterization rather than
219 accurate topographic representation and too much focus on the
220 latter outcome may lead to greater uncertainties and bias.

221 *F. Developing and Embracing New Visualization Methods*

222 The methods to visualize digital terrain modeling results have
223 not kept pace with the rapidly evolving computational resources
224 and the availability and use of fine resolution DEMs which cover
225 large areas. The map generalization projects funded as part of the
226 NED research program in the U.S. [22] and the new tangible
227 geospatial modeling system proposed by Petrasova et al. [23]
228 may help to fill this gap.

229 *G. Adopting New Computational Methods*

230 The rapid advances in computational power and changing
231 models of computing (i.e. cloud computing, cyberinfrastructure,
232 interoperability, software-as-a-service) offer new opportunities to
233 develop new analytical tools and expand the geographic extent
234 and heft of digital terrain modeling projects. Three examples can
235 be used to illustrate the potential benefits of these new methods.

236 The TerraEx [24] application, for example, is a freely
237 available, full service web application to locate landscapes that
238 are similar to a user-selected query and doubles as a convenient
239 portal to support the distribution of 3 arc-second DEMs and
240 global maps of geomorphons and terrain relief. Survilla et al.
241 [25], on the other hand, have developed a scalable high
242 performance topographic flow direction algorithm which
243 eliminated the bottleneck caused by flow direction, one of the
244 most computationally intensive functions in the current
245 implementation of TauDEM [26]. This essentially local operation
246 is transformed into a global operation to route flow across flat
247 regions, by first identifying the flat areas and then using this
248 information to reduce the number of sequential and parallel
249 iterations needed to calculate flow direction. The third and final
250 example by Qin et al. [27] proposes an efficient solution to
251 calculate the differential equation for specific catchment area
252 (SCA) proposed by Gallant and Hutchinson [28] from gridded
253 DEMs for small- and moderate-sized catchments.

254 IV. CONCLUSIONS

255 The seven innovations highlighted in the previous section
256 show how the adoption and use of modern computing platforms
257 can modify the digital terrain modeling workflows that many of
258 us have used with standalone personal computers during the past
259 few decades and thereby advance our craft. These innovations
260 can also be used to encourage the pursuit of digital terrain
261 modeling projects that will produce “actionable” knowledge and
262 outcomes. The final two applications described below show how
263 such projects can transcend multiple scales.

264 In the first study, Woodrow et al. [29] examined the impacts
265 of DEM grid resolution, elevation source data, and conditioning
266 techniques on the spatial and statistical distribution of field-scale
267 hydrological attributes for a small agricultural watershed in
268 Ontario, Canada. The results showed how the decision to use one
269 DEM conditioning technique over another and the constraints of
270 available DEM data resolution and source can greatly impact the
271 modeled surface drainage patterns for individual fields. These
272 kinds of results can help with the design of best management
273 practices for reducing soil erosion and runoff contamination
274 within agricultural watersheds and thereby in helping to manage
275 nonpoint source pollution at the source.

276 The second application is the U.S. National Water Model
 277 (NWM) project. This large, multi-disciplinary project forecasts
 278 streamflow over the continental U.S. at intervals of 1 hour, 18
 279 hours, 10 and 30 days for 2.7 million stream reaches. The NWM
 280 uses the WRF-Hydro and Noah-MP land surface models to
 281 simulate meteorological conditions and terrestrial hydrology.
 282 Several ArcGIS Hydro and TauDEM [26] terrain modeling
 283 functions are included in WRF-Hydro and these provide the
 284 essential 'glue' and are used as part of this modeling framework
 285 to route water across the land surface to the nearest stream
 286 channel. The NWM outputs can be accessed via interactive maps
 287 (<http://water.noaa.gov/map>) and once incorporated in the daily
 288 workflows of the relevant agencies (public safety, water
 289 resources, etc.), they will fundamentally change the ways in
 290 which local, state, and federal agencies prepare for and anticipate
 291 floods and related water challenges.

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